

# Common Fixed Point Theorems Of Gregus Type For Compatible Mappings In Banach Spaces

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## Abstract

In this paper, we prove a common fixed point theorem of Gregus type for compatible mappings in Banach space. Our work generalizes several earlier results on fixed points in this direction.

**Key Words:** Common fixed point, compatible mappings, weakly compatible mappings, best approximant.

**AMS Subject classification (2000):** Primary 54H25, Secondary 47H10

## 1 INTRODUCTION AND PRELIMINARIES:

The following definitions and results will be used in this paper.

In [8], Jungck defined the concept of compatibility of two mappings, which includes weakly commuting mappings (Sessa [15]) as proper sub class.

### 1.1 Definition:

Let  $X$  be a normed linear space and let  $S, T : X \rightarrow X$  be two mappings  $S$  and  $T$  are said to be compatible if, whenever  $\{x_n\}$  is a sequence in  $X$  such that  $Sx_n, Tx_n \rightarrow x \in X$ , then

$$\|STx_n - TSx_n\| \rightarrow 0 \text{ as } n \rightarrow \infty$$

In (1998), Jungck and Rhoades[10] introduced the notion of weakly compatible maps and showed that compatible maps are weakly compatible but converse need not be true.

### 1.2 Definition:

A pair of  $S$  and  $T$  is called **weakly compatible** pair if they commute at coincidence points.

### 1.3 Example:

Consider  $X = [0,2]$  with the usual metric  $d$ . Define mappings  $S, T : X \rightarrow X$  by

$$Sx = 0 \text{ if } x = 0, Sx = 0.15 \text{ if } x > 0$$

$$Tx = 0 \text{ if } x = 0, Tx = 0.3 \text{ if } 0 < x \leq 0.5, Tx = x - 0.35 \text{ if } x > 0.5$$

Since  $S$  and  $T$  commute at coincidence point  $0 \in X$ , so  $S$  and  $T$  are weakly compatible maps to see that  $S$  and  $T$  are not

compatible, let us consider a decreasing sequence  $\{x_n\}$  where  $x_n = 0.5 + \left(\frac{1}{n}\right), n = 1, 2, \dots$ . Then  $Sx_n \rightarrow 0.15, Tx_n \rightarrow 0.15$

but  $STx_n \rightarrow 0.15, TSx_n \rightarrow 0.3$  as  $n \rightarrow \infty$ . Thus weakly compatible compatible maps need not be compatible.

## 2. MAIN RESULTS:

We prove a common fixed point theorem of Gregus type for compatible mappings in Banach space. Our Theorem is improvement of results of Gregus[6], Jungck [9], Sharma and Deshpande [17].

Throughout this section, we assume that  $X$  is Banach space and  $C$  is non empty closed convex subset of  $X$ .

Now, we prove our main theorem.

### 2.1 Theorem :

Let  $S$  and  $T$  be compatible mappings of  $C$  into itself satisfying the following condition:

$$\begin{aligned} \|Tx - Ty\| \leq a\|Sx - Sy\| + b \max\{\|Tx - Sx\|, \|Ty - Sy\|\} \\ + c \max\{\|Sx - Sy\|, \|Tx - Sx\|, \|Ty - Sy\|\} \end{aligned}$$

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$$+ d \max \left\{ \|Sx - Sy\|, \|Tx - Sx\|, \|Ty - Sy\|, \frac{1}{2} (\|Ty - Sx\| + \|Tx - Sy\|) \right\} \dots(1)$$

for all  $x, y$  in  $C$  where  $a, b, c, d > 0$ ,  $a + b + c + d = 1$  and  $a + c + d < \sqrt{a}$  if  $S$  is linear and continuous in  $C$  and  $T(C) \subset S(C)$ . Then  $T$  and  $S$  have a unique common fixed point  $z$  in  $C$  and  $T$  is continuous at  $z$ .

**Proof :** Consider  $x = x_0$  be an arbitrary point in  $C$  and choose points  $x_1, x_2$  and  $x_3$  in  $C$  such that  $Sx_1 = Tx, Sx_2 = Tx_1, Sx_3 = Tx_2$

This can be done since  $T(C) \subset S(C)$ . for  $r = 1, 2, 3, \dots$  (1) leads to

$$\begin{aligned} \|Tx_r - Sx_r\| &= \|Tx_r - Tx_{r-1}\| \\ &\leq a \|Sx_r - Sx_{r-1}\| + b \max \left\{ \|Tx_r - Sx_r\|, \|Tx_{r-1} - Sx_{r-1}\| \right\} \\ &+ c \max \left\{ \|Sx_r - Sx_{r-1}\|, \|Tx_r - Sx_r\|, \|Tx_{r-1} - Sx_{r-1}\| \right\} \\ &+ d \max \left\{ \|Sx_r - Sx_{r-1}\|, \|Tx_r - Sx_r\|, \|Tx_{r-1} - Sx_{r-1}\|, \frac{1}{2} (\|Tx_{r-1} - Sx_r\| + \|Tx_r - Sx_{r-1}\|) \right\} \end{aligned}$$

which shows that, since

$$\|Sx_r - Sx_{r-1}\| = \|Tx_{r-1} - Sx_{r-1}\|,$$

we have, for  $r = 1, 2, 3, \dots$

$$\|Tx_r - Sx_r\| \leq \|Tx_{r-1} - Sx_{r-1}\|. \dots(2)$$

From (1) and (2) we have

$$\begin{aligned} \|Tx_2 - Sx_1\| &= \|Tx_2 - Tx\| \\ &\leq a \|Sx_2 - Sx\| + b \max \left\{ \|Tx_2 - Sx_2\|, \|Tx - Sx\| \right\} \\ &+ c \max \left\{ \|Sx_2 - Sx\|, \|Tx_2 - Sx_2\|, \|Tx - Sx\| \right\} \\ &+ d \max \left\{ \|Sx_2 - Sx\|, \|Tx_2 - Sx_2\|, \|Tx - Sx\|, \frac{1}{2} (\|Tx - Sx_2\| + \|Tx_2 - Sx\|) \right\} \\ &\leq a \|Tx_1 - Sx\| + b \max \left\{ \|Tx - Sx\|, \|Tx - Sx\| \right\} \\ &+ c \max \left\{ \|Tx_1 - Sx\|, \|Tx - Sx\|, \|Tx - Sx\| \right\} \\ &+ d \max \left\{ \|Tx_1 - Sx\|, \|Tx - Sx\|, \|Tx - Sx\|, \frac{1}{2} (\|Tx - Tx_1\| + \|Tx_2 - Sx\|) \right\} \\ &\leq 2a \|Tx - Sx\| + b \|Tx - Sx\| + 2c \|Tx - Sx\| + d \max \left\{ \|Tx_1 - Sx\|, \|Tx - Sx\|, \|Tx - Sx\|, \right. \\ &\quad \left. \frac{1}{2} (\|Tx - Sx_1\| + \|Tx_1 - Sx_1\| + \|Tx_2 - Sx_2\| + \|Sx_2 - Sx\|) \right\} \\ &\leq 2a \|Tx - Sx\| + b \|Tx - Sx\| + 2c \|Tx - Sx\| + d \max \left\{ \|Tx_1 - Sx\|, \|Tx - Sx\|, \|Tx - Sx\|, \right. \\ &\quad \left. \frac{1}{2} (\|Tx - Sx\| + \|Tx - Sx\| + \|Tx_1 - Sx\|) \right\} \\ &\leq 2a \|Tx - Sx\| + b \|Tx - Sx\| + 2c \|Tx - Sx\| + 2d \|Tx - Sx\| \\ &\leq \{(2a + 2c + 2d) + b\} \|Tx - Sx\| \dots(3) \end{aligned}$$

We shall now define a point

$$z = \left(\frac{1}{2}\right)x_2 + \left(\frac{1}{2}\right)x_3.$$

Since  $C$  is convex,  $z \in C$  and  $S$  being linear

$$\begin{aligned} Sz &= \left(\frac{1}{2}\right)Sx_2 + \left(\frac{1}{2}\right)Sx_3 \\ &= \left(\frac{1}{2}\right)Tx_1 + \left(\frac{1}{2}\right)Tx_2 \dots(4) \end{aligned}$$

It follows from (2), (3) and (4) that

$$\begin{aligned}
 \|S_z - S_{x_1}\| &= \left\| \left(\frac{1}{2}\right)Tx_1 + \left(\frac{1}{2}\right)Tx_2 - S_{x_1} \right\| \\
 &\leq \left(\frac{1}{2}\right) \|Tx_1 - S_{x_1}\| + \left(\frac{1}{2}\right) \|Tx_2 - S_{x_1}\| \\
 &\leq \left(\frac{1}{2}\right) \|Tx - Sx\| + \left(\frac{1}{2}\right) \{(2a + 2c + 2d) + b\} \|Tx - Sx\| \\
 &\leq \left(\frac{1}{2}\right) \{1 + (2a + 2c + 2d) + b\} \|Tx - Sx\| \quad \dots(5)
 \end{aligned}$$

By (2) and (4), we have

$$\begin{aligned}
 \|S_z - S_{x_2}\| &= \left\| \left(\frac{1}{2}\right)Tx_1 + \left(\frac{1}{2}\right)Tx_2 - S_{x_2} \right\| \\
 &\leq \left(\frac{1}{2}\right) \|Tx_2 - S_{x_2}\| \\
 &\leq \left(\frac{1}{2}\right) \|Tx - Sx\|. \quad \dots(6)
 \end{aligned}$$

By (1) and (6) we have

$$\begin{aligned}
 \|T_z - S_z\| &= \left\| T_z - \left(\frac{1}{2}\right)Tx_1 - \left(\frac{1}{2}\right)Tx_2 \right\| \\
 &\leq \left(\frac{1}{2}\right) \|T_z - Tx_1\| + \left(\frac{1}{2}\right) \|T_z - Tx_2\| \\
 &\leq \left(\frac{1}{2}\right) a \|S_z - S_{x_1}\| + \left(\frac{1}{2}\right) b \max \{ \|T_z - S_z\|, \|Tx_1 - S_{x_1}\| \} \\
 &+ \left(\frac{1}{2}\right) c \max \{ \|S_z - S_{x_1}\|, \|T_z - S_z\|, \|Tx_1 - S_{x_1}\| \} \\
 &+ \left(\frac{1}{2}\right) d \max \{ \|S_z - S_{x_1}\|, \|T_z - S_z\|, \|Tx_1 - S_{x_1}\|, \\
 &\quad \frac{1}{2} (\|Tx_1 - S_z\| + \|T_z - S_{x_1}\|) \} + \left(\frac{1}{2}\right) a \|S_z - S_{x_2}\| + \left(\frac{1}{2}\right) b \max \{ \|T_z - S_z\|, \|Tx_2 - S_{x_2}\| \} \\
 &+ \left(\frac{1}{2}\right) c \max \{ \|S_z - S_{x_2}\|, \|T_z - S_z\|, \|Tx_2 - S_{x_2}\| \} \\
 &+ \left(\frac{1}{2}\right) d \max \{ \|S_z - S_{x_2}\|, \|T_z - S_z\|, \|Tx_2 - S_{x_2}\|, \\
 &\quad \frac{1}{2} (\|Tx_2 - S_z\| + \|T_z - S_{x_2}\|) \} \\
 &\leq \left(\frac{1}{4}\right) a [1 + 2a + 2c + 2d + b] \|Tx - Sx\| + \left(\frac{1}{2}\right) b \max \{ \|T_z - S_z\|, \|Tx - Sx\| \} \\
 &+ \left(\frac{1}{2}\right) c \max \left\{ \frac{1}{2} (1 + 2a + 2c + b + 2d) \|Tx - Sx\|, \|T_z - S_z\|, \|Tx - Sx\| \right\} \\
 &+ \left(\frac{1}{2}\right) d \max \left[ \frac{1}{2} (1 + 2a + 2c + b + 2d) \|Tx - Sx\|, \|T_z - S_z\|, \|Tx - Sx\|, \right.
 \end{aligned}$$

$$\begin{aligned} & \frac{1}{2} \left\{ (2 + 2a + 2c + 2d + b) \|Tx - Sx\| + \|Tz - Sz\| \right\} + \left( \frac{1}{4} \right) a \|Tx - Sx\| \\ & + \left( \frac{1}{2} \right) b \max \{ \|Tz - Sz\|, \|Tx - Sx\| \} + \left( \frac{1}{2} \right) c \max \left\{ \frac{1}{2} \|Tx - Sx\|, \|Tz - Sz\|, \|Tx - Sx\| \right\} \leq \lambda \|Tx - Sx\| \dots(7) \\ & + \left( \frac{1}{2} \right) d \max \left\{ \frac{1}{2} \|Tx - Sx\|, \|Tz - Sz\|, \|Tx - Sx\|, \frac{1}{2} (2 \|Tx - Sx\| + \|Tz - Sz\|) \right\} \end{aligned}$$

where

$$\begin{aligned} \lambda &= \left( \frac{1}{4} \right) a [2 + 2a + 2c + 2d + b] + b + \frac{1}{4} c [1 + 2a + 2c + b + 2d] \\ &+ \frac{1}{2} c + \frac{1}{4} d [2 + 2a + 2c + b + 2d] + d \\ &< \frac{1}{4} a (3 + \sqrt{a}) + \frac{1}{4} c (2 + \sqrt{a}) + b + \frac{1}{2} c + \frac{d}{4} (3 + \sqrt{a}) + d \\ &< \frac{a}{4} + \frac{3a}{4} + b + c + d \\ &= a + b + c + d = 1 \end{aligned}$$

So we have  $0 < \lambda < 1$ .

Since  $x$  is an arbitrary point in  $C$ , from (7), it follows that there exists a sequence  $\{z_n\}$  in  $C$  such that

$$\|Tz_0 - Sz_0\| \leq \lambda \|Tx_0 - Sx_0\|,$$

$$\|Tz_1 - Sz_1\| \leq \lambda \|Tz_0 - Sz_0\|,$$

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$$\|Tz_n - Sz_n\| \leq \lambda \|Tz_{n-1} - Sz_{n-1}\|,$$

which yield that

$$\|Tz_n - Sz_n\| \leq \lambda^{n+1} \|Tx_0 - Sx_0\|,$$

and so we have

$$\lim_{n \rightarrow \infty} \|Tz_n - Sz_n\| = 0 \dots(8)$$

Setting  $K_n = \left\{ x \in C : \|Tx - Sx\| \leq \frac{1}{n} \right\}$

for  $n = 1, 2, \dots$  then (8) shows that

$$K_n \neq \emptyset \quad \text{for } n = 1, 2, \dots$$

and  $K_1 \supset K_2 \supset K_3 \supset \dots$

obviously, we have  $\overline{TK_n} \neq \emptyset$  and

$$\overline{TK_n} \supset \overline{TK_{n+1}} \quad \text{for } n = 1, 2, \dots$$

for any  $x, y$  in  $K_n$  by (1), we have

$$\begin{aligned} \|Tx - Ty\| &\leq a \|Sx - Sy\| + n^{-1}b + c \max \{ \|Sx - Sy\|, n^{-1} \} \\ &+ d \max \left\{ \|Sx - Sy\|, n^{-1}, \frac{1}{2} (n^{-1} + \|Sx - Sy\| + n^{-1} + \|Sx - Sy\|) \right\} \\ &\leq a \|Sx - Sy\| + n^{-1}b + c \max \{ \|Sx - Sy\|, n^{-1} \} \\ &+ d \max \{ \|Sx - Sy\|, n^{-1}, (n^{-1} + \|Sx - Sy\|) \} \\ &\leq a (2n^{-1} + \|Tx - Ty\|) + n^{-1}b + c (2n^{-1} + \|Tx - Ty\|) + d (3n^{-1} + \|Tx - Ty\|) \\ &= [a + c] 2n^{-1} + [a + c + d] \|Tx - Ty\| + n^{-1}b + 3n^{-1}d \end{aligned}$$

Therefore,

$$\|Tx - Ty\| \leq n^{-1} \{2[a + c] + b + 3d\} (1 - a - c - d)^{-1}$$

Thus we have

$$\lim_{n \rightarrow \infty} \text{diam}(\overline{TK_n}) = \lim_{n \rightarrow \infty} \text{diam}(TK_n) = 0$$

By Cantor's theorem, there exists a point  $u$  in  $C$  such that

$$\bigcap_{n=1}^{\infty} (\overline{TK_n}) = \{u\}.$$

Since  $u \in C$  for each  $n = 1, 2, \dots$  there exists a point  $y_n$  in  $TK_n$  such that

$$\|y_n - u\| < n^{-1}$$

Then there exists a point  $x_n$  in  $K_n$  such that

$$\|u - Tx_n\| < n^{-1}$$

and so  $Tx_n \rightarrow u$  as  $n \rightarrow \infty$ .

Since  $x_n \in k_n$ , we have also

$$\|Tx_n - Sx_n\| < n^{-1}$$

and so  $Sx_n \rightarrow u$  as  $n \rightarrow \infty$ .

Since  $S$  is continuous  $STx_n \rightarrow Su$  and  $SSx_n \rightarrow Su$  as  $n \rightarrow \infty$ .

Moreover  $\|TSx_n - STx_n\| \rightarrow 0$  as  $n \rightarrow \infty$ .

Since  $S$  and  $T$  are compatible and  $Tx_n \rightarrow Sx_n \rightarrow u$  as  $n \rightarrow \infty$ , we have  $TSx_n \rightarrow Su$ .

By (1), we have

$$\begin{aligned} \|Tu - Su\| &\leq \|Tu - TSx_n\| + \|TSx_n - Su\| \\ &\leq a\|Su - SSx_n\| + b \max\{\|Tu - Su\|, \|TSx_n - SSx_n\|\} \\ &\quad + c \max\{\|Su - SSx_n\|, \|Tu - Su\|, \|TSx_n - SSx_n\|\} \\ &\quad + d \max\{\|Su - SSx_n\|, \|Tu - Su\|, \|TSx_n - SSx_n\|, \\ &\quad \frac{1}{2}(\|TSx_n - Su\| + \|Tu - SSx_n\|)\} + \|TSx_n - Su\| \end{aligned}$$

Letting  $n \rightarrow \infty$ , we obtain

$$\begin{aligned} \|Tu - Su\| &\leq a\|Su - Su\| + b \max\{\|Tu - Su\|, \|Su - Su\|\} \\ &\quad + c \max\{\|Su - Su\|, \|Tu - Su\|, \|Su - Su\|\} \\ &\quad + d \max\{\|Su - Su\|, \|Tu - Su\|, \|Su - Su\|, \\ &\quad \frac{1}{2}(\|Su - Su\| + \|Tu - Su\|)\} + \|Su - Su\| \\ &= (b + c + d)\|Tu - Su\| \\ &= (1 - a)\|Tu - Su\|. \end{aligned}$$

So we have  $Tu = Su$ .

Thus  $TSu = STu$  and  $TTu = TSu = STu$  since  $S$  and  $T$  are compatible. Furthermore, we have

$$\begin{aligned} \|TTu - Tu\| &\leq a\|STu - Su\| + b \max\{\|TTu - STu\|, \|Tu - Su\|\} \\ &\quad + c \max\{\|STu - Su\|, \|TTu - STu\|, \|Tu - Su\|\} \\ &\quad + d \max\{\|STu - Su\|, \|TTu - STu\|, \|Tu - Su\|, \\ &\quad \frac{1}{2}(\|Tu - STu\| + \|TTu - Su\|)\} \\ &= (a + c + d)\|TTu - Tu\| \end{aligned}$$

This leads to  $\|TTu - Tu\| = 0$  since  $(a + c + d) < \sqrt{a}$ .

Let  $z = Tu = Su$ .

Then  $Tz = z$  and  $Sz = STz = TSz = Tz = z$ .

Thus  $z$  is a unique common fixed point of  $T$  and  $S$ . The uniqueness of  $z$  is a consequence of inequality (1). Now, we show that  $T$  is continuous at  $z$ . Let  $\{y_n\}$  be a sequence in  $C$  such that  $y_n \rightarrow z$ .

Since  $S$  is continuous,  $Sy_n \rightarrow Sz$ , By (1), we have

$$\begin{aligned} \|Ty_n - Tz\| &\leq a\|Sy_n - Sz\| + b \max\{\|Ty_n - Sy_n\|, \|Tz - Sz\|\} \\ &\quad + c \max\{\|Sy_n - Sz\|, \|Ty_n - Sy_n\|, \|Tz - Sz\|\} \\ &\quad + d \max\{\|Sy_n - Sz\|, \|Ty_n - Sy_n\|, \|Tz - Sz\|, \frac{1}{2}(\|Tz - Sy_n\| + \|Ty_n - Sz\|)\} \\ &\leq a\|Sy_n - Sz\| + b \max\{\|Ty_n - Tz\| + \|Tz - Sy_n\|\} \\ &\quad + c \max\{\|Sy_n - Sz\|, \|Ty_n - Tz\| + \|Tz - Sy_n\|\} \\ &\quad + d \max\{\|Sy_n - Sz\|, \|Ty_n - Tz\| + \|Tz - Sy_n\|, \|Tz - Sz\|, \\ &\quad \quad \quad \frac{1}{2}(\|Tz - Sy_n\| + \|Ty_n - Sz\|)\} \\ &\leq a\|Sy_n - Sz\| + b\{\|Ty_n - Tz\| + \|Sz - Sy_n\|\} + c\{\|Ty_n - Tz\| + \|Sz - Sy_n\|\} \\ &\quad + d\{\|Ty_n - Tz\| + \|Sz - Sy_n\|\}, \\ \|Ty_n - Tz\| &\leq (a + b + c + d)\|Sy_n - Sz\| + (b + c + d)\|Ty_n - Tz\| \\ &\leq (a + b + c + d)(1 - b - c - d)^{-1}\|Sy_n - Sz\| \end{aligned}$$

Therefore, we have  $Ty_n \rightarrow Tz$  and so  $T$  is continuous at  $z$ .

This completes the proof.

As a consequences of our Theorem 2.1, we have the following results.

**2.2Corollary:**

Let  $S$  and  $T$  be compatible mappings of  $C$  into itself satisfying the following condition:

$$\begin{aligned} \|Tx - Ty\| &\leq a\|Sx - Sy\| + b \max\{\|Tx - Sx\|, \|Ty - Sy\|\} \\ &\quad + c \max\{\|Sx - Sy\|, \|Tx - Sx\|, \|Ty - Sy\|\} \end{aligned}$$

for all  $x, y$  in  $C$  where  $a, b, c > 0$ ,  $a + b + c = 1$  and  $a + c < \sqrt{a}$  if  $S$  is linear and continuous in  $C$  and  $T(C) \subset S(C)$ . Then  $T$  and  $S$  have a unique common fixed point  $z$  in  $C$  and  $T$  is continuous at  $z$ .

Corollary 2.2 shows the result of Sharma and Deshpande [16], which obtain by putting  $d = 0$ .

Now if  $b=0, c=0$  then we get the following corollary

**2.3Corollary:**

Let  $S$  and  $T$  be compatible mappings of  $C$  into itself satisfying the following condition:

$$\|Tx - Ty\| \leq a\|Sx - Sy\| + (1 - a) \max\{\|Tx - Sx\|, \|Ty - Sy\|\}$$

for all  $x, y$  in  $C$ ,  $0 < a < 1$ , if  $S$  is linear and continuous in  $C$  and  $T(C) \subset S(C)$ , Then  $T$  and  $S$  have a unique common fixed point  $z$  in  $C$  and  $T$  is continuous at  $z$ .

**2.4 Remark:**

Corollary (2.3) also proves continuity of  $T$ , so it improves the result of Jungck[9].

if we put  $a = b = c = 0$  then we get the following result

**2.5 Corollary:**

Let  $S$  and  $T$  be compatible mappings of  $C$  into itself satisfying the following condition:

$$\|Tx - Ty\| \leq d \max\{\|Sx - Sy\|, \|Tx - Sx\|, \|Ty - Sy\|, \frac{1}{2}(\|Ty - Sx\| + \|Tx - Sy\|)\}$$

for all  $x, y$  in  $C$  where  $0 \leq d < 1$ , if  $S$  is linear and continuous in  $C$  and  $T(C) \subset S(C)$ . Then  $T$  and  $S$  have a unique common fixed point  $z$  in  $C$  and  $T$  is continuous at  $z$ .

To demonstrate the validity of our Theorem 2.1, we have the following example

### 2.6 Example:

Let  $X = R$  and  $C = [0,1]$  with the usual norm. Consider the mappings  $T$  and  $S$  on  $C$  defined as  $Tx = \frac{1}{4}x$  and  $Sx = \frac{1}{2}x$  for all  $x \in C$

$$\text{Then } T(C) = \left[0, \frac{1}{4}\right] \subset S(C) = \left[0, \frac{1}{2}\right].$$

It is easy to see that  $S$  is linear and continuous.

Further,  $T$  and  $S$  are compatible if  $\lim_{n \rightarrow \infty} x_n = 0$ , where  $\{x_n\}$  is a sequence in  $C$  such that  $\lim_{n \rightarrow \infty} Tx_n = \lim_{n \rightarrow \infty} Sx_n = 0$  for some  $0 \in C$ .

If we take  $a = 1/9, b = 13/18, c = 3/18, d = 0$  we see that the condition (1) of our Theorem 3.1, is satisfied also we have  $a + b + c = 1$  and  $a + c < \sqrt{a}$ .

Thus all the conditions of Theorem 3.1 are satisfied and 0 is the unique common fixed point of  $S$  and  $T$ .

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